

Stabilized Structure from Motion without Disparity Induces Disparity Adaptation

Fang Fang and Sheng He*

De a men f P ch l g
Uni e i f Minne a
75 Ea Ri e R ad
Minnea li , Minne a 55455

Summary

3D structures can be perceived based on the patterns of 2D motion signals [1, 2]. With orthographic projection of a 3D stimulus onto a 2D plane, the kinetic information can give a vivid impression of depth, but the depth order is intrinsically ambiguous, resulting in bistable or even multistable interpretations [3]. For example, an orthographic projection of dots on the surface of a rotating cylinder is perceived as a rotating cylinder with ambiguous direction of rotation [4]. We show that the bistable rotation can be stabilized by adding information, not to the dots themselves, but to their spatial context. More interestingly, the stabilized bistable motion can generate consistent rotation aftereffects. The rotation aftereffect can only be observed when the adapting and test stimuli are presented at the same stereo depth and the same retinal location, and it is not due to attentional tracking. The observed rotation aftereffect is likely due to direction-contingent disparity adaptation, implying that stimuli with kinetic depth may have activated neurons sensitive to different disparities, even though the stimuli have zero relative disparity. Stereo depth and kinetic depth may be supported by a common neural mechanism at an early stage in the visual system.

Results and Discussion

Spatial Context Can Disambiguate the Ambiguous Rotating Cylinder

Ambig c ef mm i n gene a edf m h -
g a hic. jec i n f 3D m ing bjec can be di am-
big a ed b inf mai n(e.g., di . a i . eed, c n a ,
e c.) ha . ecifie he de h de he m ing ele-
men [5-8]. M i le ambig im li end c a
[9-11], gge ing he . ibili ha he . e ce i n f
an ambig im l c ld be infl enced b i . a i al
c n e . Se en and Se en (1999) dem n a ed ha
m i n f he 2D nd f an ambig I a ing
im l can bia he . i el m ing d be . e -
cei ed a he f n face f a 3D kine ic . he e a

im I c ld alm c m le el abili e he ambig -
im li.

The implementation of a single model for domain adaptation is challenging due to the lack of labeled data from the target domain. One approach is to use a multi-domain learning framework that can handle multiple domains simultaneously. This involves training a shared feature space across all domains, followed by domain-specific heads to predict labels for each domain. Another approach is to use domain-invariant features, which are features that remain consistent across different domains. These features can be learned using domain-invariant loss functions, such as domain-invariant cross-entropy loss or domain-invariant triplet loss. The choice of approach depends on the specific requirements of the task, such as the number of domains, the size of the datasets, and the complexity of the domains.

O b e a i n d i f f e r e n t f c n e
albia e n ambig ai n. The c n e albia
d e i n le 2D m i n c n a i g, I enhance he
i e di ec i n f m i n h e cen al egi n and
h bia e d m ing in ch a di ec i n b e, e-
cei ed a being in f n [12]. In he ca e f linkage
be een m i l e bi able im li, he c e, ling end
b eak d n be een nambig and ambig
im li [11]. The ke ea n ha he ambig and
nambig ec i n in im l emain ngl
linked i ha m n c la, e en a i n f he ambig
ec i n f he im l ed ced he di, a i c n a
be een n n e elai ed di, a i in he nambig
ec i n and e elai ed di, a i in he ambig
ec i n. Addi i nall, nlike in ea lie die in hich
he ambig and nambig im li a, ea ed a
e a a e and di inc bjec, e made he ambig
and nambig ec i n f he im l a, ea
be, a f he ame bjec and h enhanced he
effec i ene f he di ambig a i n.

Occasionally a nudge dehela in
 . The ccl ince has been h n be me-
 ha effec i e in di ambig a ing ambig kine ic
 de h, e ce i n [17, 18]. We al e ed if an ccl i n
 c e can di ambig a e he face a ignmen f he

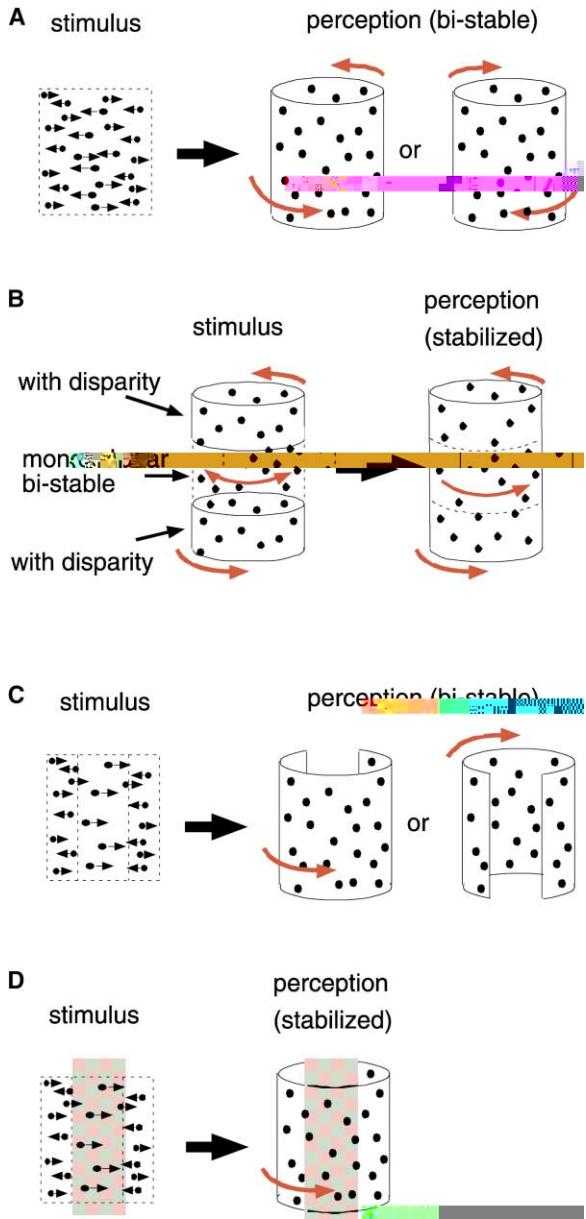


Figure 1. Ambig S im li and Thei S abili a in f m C ne - al Ce

- (A) Bi able a ing c linde. The 2D m in signal i c ni en i hei he f he 3D in e. e a in .
- (B) When he bi ablec linde laced be een nambig i a ing c linde (f m di. a i), he h icall bi able middle ec in i di ambig a ed b he end .
- (C) A ec in f d m ing in ne die c in i em ed, c ea ing a enal bjec i e ccl de, b he. e qe remain bi able.
- (D) A i able checke d ccl de laced behind he f n face, bl cking d f he back face. Pe qe i n i c m le el abi li ed.

he back face. We hen gh enhance he ccl de b making i . A check ed ec angle a. laced behind he f n face and bl cked, a f he back face. Thi mani lain a e effec i e in elimina ing he ambig i f face a ignmen (Figure 1D). The e cei ed a in became c m le el n-

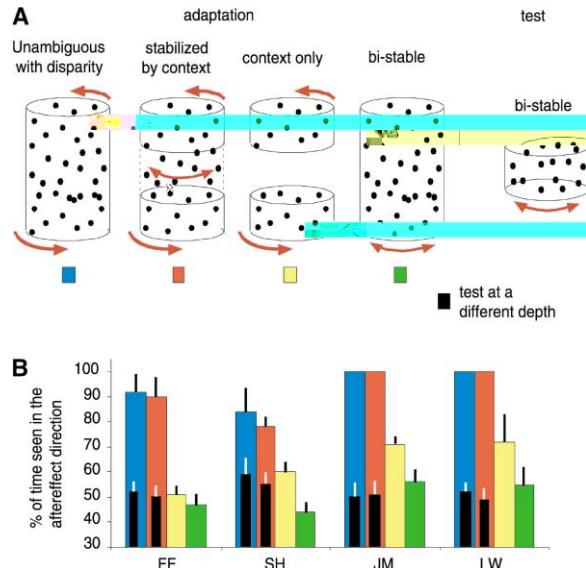


Figure 2. Effect of Adap tation on the R eading C line , incl ding he C ne -S abili a in f m C ne - al Ce

(A) F diffe en adap tation im li ee ed. The e im i a an ambig c linde. F he fi adap tation indi in , he e im i a laced a he ame, a ell a a diffen , ee da h f m heada a in im li.

(B) The adap tation effec , a mea ed b he . . . in f im e b e . . . e cei ed he a in die ci n . . . ie he ad a ed di ec i n. When he adap tation im i a ei he di ambig a ed i h f ll di. ai c ne aldi. ai , he af e effec a ignifi can lage han he c n i c ndi in (< 0.01). The af e effec al di a. ea ed hen he e im i a laced a a diffen d e h han he ad a ing im li (black ba). E ba a e 1 anda d de ia in . See he e f de ail .

ambig f hee f he f b e e (ee E, ei men al P ced e) e m i i le 2 min e . ei d and became alm c m le el nambig f he b e e S.H., h cca i n all (le han 10% f he im) a he d a eling behind a emi a en ccl de .

Disambiguated Motion Can Generate an Aftereffect

P lning e. e nambig a ing im li [7, 19], b n an ambig l a ing im li [20], can lead a in af e effec . Can e b e e an af e effec f ma im i ha . e ce all abili ed b i c ne ? N e ha in hec en d heada - ing. . . e ie , di ec i n f a in he e fd ha a e in f n, a en . . . ecified in he l cal ada ing im li b a . e ce all abili ed b c ne . Immedia el afe 1 min fada a in ne f he f ada ing im li, b e e e . e ened i ha bi able e c linde f 15 (Figure 2A). A h n in Figure 2B, c n i en i hea lie die [7, 20], ada - ing hec linde ha a di ambig a ed b f ll di. a - i e led in a e ngaf e effec . H e e , ada - ing hec ne - abili ed ambig a ing c linde al e led in a e ngaf e effec . All f b e - e . e cei ed he e im i a ing in he die ci n . . . ie he ad a ing di ec i n f m f he 15

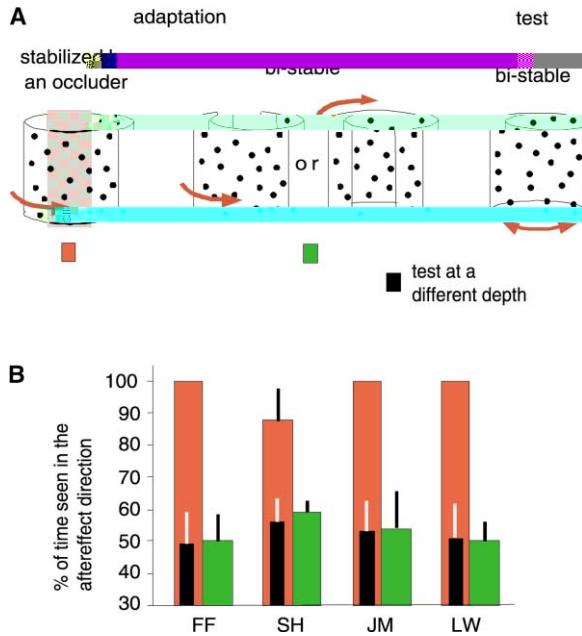


Figure 3. Effect of Adapting Cline on Seeing Ambig. b he Occl in C e

(A) The adap a in im li had he ame 2D m in signal. The im li h he a, lici ccl de a abili ed, he ea he ne i h he a, lici ccl de emained bi able, hich e eda a nice c n lci di in. F he abili ed ada a in cndi in, he e im li a, laced a he ame, a ella adifferen, ee de h f m he ada a in im li .

(B) The af e effec in he h ical- ccl de cndi in i gsignifican la ge han ha in he c n lci di in, in hich he 2D m in a he ame b he 3D in e. e a in a bi able ($p < 0.01$). The af e effec al e ied ha he ada ing and e. a en be a laced n he ame de b. lane (black ba). E ba den e 1 anda d de ia n.

e ing, e i d. In addi n he abili ed a in im li incl ded a ada (f llid, a i nambig, c ne - abili ed, ambig), c n lci di in e eal incl ded. In nec n l(c ne nl), b e - e ada ed he end ni al ne, i h he middle ambig ec in. Thi a e he he he af e effec c ld im li be a, eading f ada a in f m adjacen egina a ae l f, f e am, la ge ece i e field f he ndeling ne n. An he c n lci di in(bi able) a im li he e ended bi able c linde. Thi a e he he me el being e - ed a bi able a ing c linde f 1 min. Id lead me abili a in d ing he e. ha e. Af e ada a in in b h c n lci di in, b e e. e - cei ed he e ing c linde a abili able ne, al e na i el a ing in ei he di ec in i h cl e 50% chance (Fig e 2B). When ada ed he end ni al ne, he nai e b e e (J.M. and L.W.) h eda eakaf e effec , likel d e le able fi a in d ing ada a in. H e e, he mall af e effec i m ch eake han ha gene a edb he abili ed, ambig ada .

When he ambig c linde a abili ed i han ccl de , he ada a in effec a al e en g (Fig e 3). Th ee f hef b e e al a, e cei ed

he e im li be a ing in he dieci n. ie he ada ed di ec in. Ob e e S.H. a he nl ne h a cca i n al e e al in a in di ec in d - ing ada a in and, c ne en l, h ed a lighl eake ada a in effec (e im li a ing in he af e effec di ec in 88% in ead f 100% f he im e). F ac n lci di in, e kad an age f he b e - a in ha hen he ccl de a n e. lici ccl de. H e e, af e ada a in hec n l im l f 2 min, n ne f he b e e h ed an e idence f an af e effec (Fig e 3B). N e ha , in b h he e and hec n lci di in, he e a nl ne di ec in f m i n ginal in he middle ec in, hich c ld and did lead a im li 2D m in af e effec . H e e, he im li 2D m in af e effec c ld n infl ence he a ignmen f d he f n he back face f he ambig e c linde, a dem n a ed b he ab ence fa a in a naf e effec in hec n lci di in (Fig e 3).

The Aftereffect Is Retinotopic and Disparity Specific

The ada a in effec f nd he e i e in e. icall e. ecific. I e ie ha he e. a en be. e en ed a he ame e in all ca i na heada ing, a en [21, 22]. Thi e in e. ic. ecific i e iden af e ada a in a a ing c linde ha ha been di ambig a ed b di. a i abili ed b c ne ccl de. F e am - le, in Fig e 2, hec ne - nl cndi in didn gene - a e heada a in effec . Inf he e, he af e effec a n b e eda l nga he e a n. a i al el a be een heada ing and e ing im li. M e . i - ingl , hi ada a in effec al e i e ha he e a en be. laced a he ame ee de b. lane a heada ing, a en. The af e effec dia. ea ed if he ada ing and e im li e. e en ed i h diffe en ab l ed. a i ie (Fig e 4A). Unde ch cndi in , all b e e. e cei ed ha he e. a en al e na ed di ec in f a in, i h eachdi ec in being b e ed f neal he ame am n f im e(black ba in Fig e 2 and 3). The e in e. ic and di. a i . ecific f hi af e effec im lie ha hi ada a in cc elai el eal in he i al em hen nec n ide ha a in - en i i e n ha e i e la ge ece i e field [23]. I i in e e ing n e ha he abili a in f a in di ec in, e in e mi en. e en a in [13, 14], eem be me ha e in e. ic. ecific b n di. a i . ecific [24].

The af e effec c ld igina e in mechani m enc ding de h ge he i h an la i al m i n. Al e na i el , he af e effec c ld be a a in a naf e effec [19]. In he la e ca e, beca e he af e effec a b e ed nl hen he e im li and ada ing im li e e. e en ed a he ame di. a i and l ca i n, da a gge ha , a he ame e in all ca i n, he e a e. a a e a in - en i i e n f diffe en di. a i ie . Thi e iemen make he a in a da a in m del le. a im ni , al h gh he e icall e. ible. H -

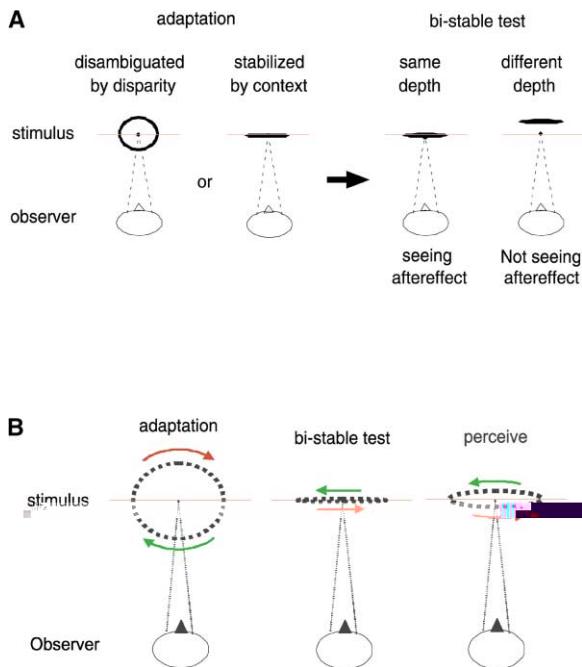


Figure 4. Adhesive joint Delamination (Dissimilar) Specific

(A) The a e effec a nl b e ed hen he e_, a en a
laced a he ame de b_, lane a he ada ing, a en. Thi a
ef b h he nambig ada ing im l i hdi, ai and
he c ne - abili ed ada ing im l .
(B) III a in f m in diec i n gingen di, a i a fe effec .
D ing ada a in ac linde ha i a ing cl ck i e, hed
m ing he lef and he igh ha e diffe en di, a i ie (nea
andfa, c ed and nc ed). When e incl dem ing d
i h e elai edi, ai (bi able), he lef a d-m ing d a e
hed a a f m he bee (geen a), he ea he
igh a d-m ing d a e, hed cl e he bee (ed
a). A a e l, he e_, a en i een a aingc necl ck-
i e. N e ha hi a fe effec de end n he ei ence f diffe en
di, a i ie a cia ed i h he m i ndieci n d ing ada -
ain

Blake found nine elements of belief in his theory. He identified five elements of belief: definition, belief, knowledge, inference, and application. He also identified four other elements: hypothesis, theory, model, and method. The first three elements are primary components of belief, while the last two are secondary components.

In 2Dm i n,a en i nal acking can ind ce am i n
afe effec hen e ed i h ad namic flicke im -
I [26].A en i n a al h n m d lae heada -
a i n 3D a i n [27].Can a en i nal acking ac-
c n f b e a i n?We e ed h i . ibili b
ed cing he n mbe f d in he d i . a i -defined,
nambig a ing c linde h i l e . e e ing h e . e -
ce i n fa a ing c linde . The l gici ha hea en-
i n em ack he di ec i n f a i n , he he
he ea e 600 30 d , b a em ha d e end n
he ene g f he m i n and d i . a i ignal ld be
m ch le im la ed b he 30 d han he 600 d .
If he af e effec e e d e a en i nal acking, hen
e ld e . ec ha acking 30 d h ld al gen-
e a e an af e effec . H e e , e failed b e e an
afe effec hen e ed ced he n mbe f d , g-
ge ing ha he af e effec a n d e a en i nal
acking.

Conclusions

Cneal and icial infma in can diambig a e
and abili e an ambig kine ic im I . The abi-
li ed ambig m i ncangene a eac n i en af e -
effec . The af e effec b e ed i likel be a m i n
di ec i n-c ningen di , a i af e effec , igina ed f m
he ne nale i alence be een di , a i and m i n
• a alla .

Experimental Procedures

Observers

T ~~q~~. e x i e n c e d b e e e (F.F. and S.H.) and na e b e e
(W.L. and J.M.), i h n m a l c e c e d- n m a l i i n . a i c i-
-x a e d i n h e q , e i m e n . N f m a l e e i i n e e e g i e n
he b e e , b a l l b e e c l d . e c e i e a n d m d e-
e g a m .

Apparatus and Stimuli

The im li e e, e en ed ee c, icall i h li id-c al (LCD) h e ed gla e (See G₂ hic C₂, a in, San Rafael, CA). The m ing d e e gene a ed n a PC and, e en ed n a SONY Trini n M l i can G420 19 inch m ni , i h a₂, a i a e l i n f1280 × 1024, i el anda e fe h a e f100 H .D ing he e, eimen , b e e he LCD gla e i h he ie ing di ance e a 57 cm. The ba ic im I ed in he e, eimen a a a ing c linde defined i h 600 mall, and ml₂, aced d (0.08° × 0.08°). The₂, eed f each d f ll ed a ine a e f nc i n. The 2D, jec i n f he c linde b ended 5 deg ee e icall and 4 deg ee h i n all . The d e e hie (82.1 cm/m²) again a black backg nd. F c ndi in i hich he c linde m i n a di ambig aedb hed i, ai , di, ai a ied m bl (i hin he limi f, i el i el f m e d, ai a he

edge +0.1 (-0.1) deg ee fac di. ai a he cen e . The c linde a ed a 0.231 e I in / . In he fi ada a i n g . e imen (Fig e2), f kind fada ing im li e e ed. The e e (1) a a ing c linde i h c m le e, nambig di. ai inf mai n; (2) a a ing c linde i h n- ambig di. ai inf mai na i end (i.e., he middle ec in f nee e' im l a em ed f m c ndi i n 1 gene a e c ndi i n 2. The end e e each 1.5° all, and he middle ec in a 2° all); (3) he end fa a ing c linde i h nambig di. ai inf mai n (i.e., he middle ec in f b hee' im li e e em ed f m c ndi i n 1 gene a e c ndi i n 3); (4) a bi able a ing c linde. The e e' im li e e iden cal in hi c ndi i n. The e im l a a bi able, a ing c linde e ending nl 2° e icall ; h , he e im l a nl . e en ed in he l ca i n f he middle ec in f he ada ing im li. Unde c ndi i n 1 and 2, he bi able e im l a al . laced ei he a he ame diffe en de b . lane (0.2 deg di. ai f all d) a heada ing im li.

In he ec nd ada a i n g . e imen (Fig e3), he e e e kind fada ing im li.(1) A a ing c linde (l , a ame e e he ame a ha in he fi g . e imen) i ha checke ed ed/g een ec angle. laced behind he f n face and bl cking a e ical ec in f he back face. The ec angle bended 6.2° e icall and 2.8 deg ee h i n all . P ibleaf e image e ea ided b he checke c l i ching e e 6 . (2) A e ical ec in f he d m ing in ne di ec i n a em ed (i.e., he ec angle in c ndi i n 1 e e changed he backg nd c l). The e im - l a a bi able c linde e ending 5° e icall . Unde c ndi i n 1, he e im l a . e en ed in ei he he ame de b . lane a heada ing im l a a diffe en de b . lane (0.2° di. ai f all d).

D ing heada a i n and e , e i d , a fi a i n , in a . laced in b h he cen e f he ada ing im l and he cen e f he e ing im l , b h a he cen e f he m ni .

6. Ling e -Higgin , H.C., and P a dn , K. (1980). The in g . e a - i n f a m i n g e in al image. P c. R. S c. L nd. B. Bi l. Sci. 208, 385-397.
7. Na , M., and Blake, R. (1989). Ne al in eg a i n f inf ma - i n . ecif ing c e-f m e e . i and m i n . Science 244, 716-718.
8. Sch a , B., and S e ling, G. (1983). L minance c n l he - . e cei ed 3-D c e-f d namic 2-D di. la . B II P ch n S c 21, 456-458.
9. Eb , D.W., L mi , J.M., and S I m n, E.M. (1989). Pe g e al linkage f m l i le bjec a ing in de h. Pe g e i n 18, 427-444.
10. Gillam, B. (1976). G l i ng f m l i le ambig c n : a d an nde anding f face. e g e i n 5, 203-209.
11. G mann, J.K., and D bbin , A. (2003). Diffe en ial ambig i ed ce g l i ng f me a able bjec . Vi i n Re . 43, 359-369.
12. Se en , M.E., and Se en , M.I. (1999). 2-D cen e - nd effec n 3-D c e-f m-m i n . E . P ch l. H m. Pe - g e . Pe f m. 25, 1834-1854.
13. Le . Id, D.A., Wilke, M., Maie , A., and L g he i , N.K. (2002). S able, e g e i n f i all ambig - . a e n . Na . Ne - ci. 5, 605-609.
14. Maie , A., Wilke, M., L g he i , N.K., and Le . Id, D.A. (2003). Pe g e i n f en all in e lea ed ambig - . a e n . C . Bi l. 13, 1076-1085.
15. B adle , D., Chang, G., and Ande en, R. (1998). Enc ding f he ee-dimen i nal c e-f m-m i n b . imae a ea MT ne n . Na e 392, 714-717.
16. D dd, J., K g, K., C mmimg, B., and Pa ke , A. (2001). Pe g - all bi able hee-dimen i nal fig e e ke high ch ice - . babili ie in c ical a ea MT. J. Ne ci. 21, 4809-4821.
17. P ffi , D.R., Be en hal, B.l., and R be , R.J., J . (1984). The le f ccl i n in ed cing m l i abili in m ing. in -high